# On Some Properties of ARMA(1,1) Model Fitting 

# to AR(2) Processes 

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#### Abstract

This paper gives a discussion on a misspecified ARMA(1,1) model fitting to an AR(2) process. The problem concerning a number of globally and locally maximal points of the conditional likelihood function is investigated when the sample size tends to infinity. We shall detect the conditions of $\operatorname{AR}(2)$ parameters on which the $\operatorname{ARMA}(1,1)$ conditional likelihood function has more than one locally maximal points in the stationary and invertible parameter space.


Keywords: ARMA(1,1) model fitting, AR(2) process, misspecification, locally minimal points, Catastrophe Theory.

## 1. Introduction

This paper is a sequel to "On a moving average time series model fitting" contributed with Mr. Kenji Aoki in 1991 ([9]).

In time series analysis, we usually apply the suitable linear model for a given time series data to predict a future value using the model. When fitting a model to the data, the parameters of a model will be estimated, and then we assume some probability distribution and generally the maximum likelihood method is used. If a true model is fitted to a process, then its unknown parameters can be precisely estimated. But when a model is incorrect, the statistical properties of the estimators will be known very little. The problem concerning maximum likelihood estimation of misspecified models has been investigated by many authors. In particular, the asymptotic properties (consistency) of the estimators of the parameters of a misspecified ARMA model have been discussed ([7]).

Also it is known that when we fit an MA(1) model to some special time series data which is not followed by MA(1) process, the MA(1) parameter does not have an unique Gaussian quasi-maximum likelihood estimator. Tanaka and Huzii [10] have given the conditions of $\operatorname{AR}(2)$ parameters on which the MA(1) quasi-likelihood function has more than one local maximal points in the invertible parameter space ( $-1,1$ ). Furthermore, Tanaka and Aoki [9] gave the region for the $\mathrm{AR}(2)$ parameters on which the $\mathrm{MA}(1)$ quasi-likelihood function has more than one local maximal points in the parameter space. In this case, maximizing the likelihood function is equivalent to minimizing the following function $\mathrm{S}(x ; a, b)$ when the data length is large (see [10]). Here $x$ is an MA(1) parameter and $a$ and $b$ are $\operatorname{AR}(2)$ parameters.

$$
\begin{equation*}
S(x ; a, b)=\frac{1+b-a(1-b) x-b(1+b) x^{2}}{(1-b)\left(1-a^{2}+2 b+b^{2}\right)\left(1-x^{2}\right)\left(1+a x+b x^{2}\right)} \tag{1.1}
\end{equation*}
$$

From Tanaka and Huzii [10], we have two minimal points of the function $S(x ; a, b)=S(x)$, say. For example, in the case of an $\mathrm{AR}(2)$ process with $\mathrm{a}=-0.1, \mathrm{~b}=0.8$, the function $S(x)$ has a graph shown in the following figure.


Figure 1. Graph of $S(x ; a, b)$ with $a=-0.1, b=0.8$.

In order to have the conditions on which the function has two local minimal points in the parameter space, we should consider the differentiation $D S(x)=0$. And we specified the case where the solution of the equation $D S(x)=0$ changed from three to two. That is, the value of the resultant ([5]) was able to formalize the contour line for zero (the bifurcation set). We set the domain D1 with a deep color surrounded with the curve of the shape of a wedge given in the upper part of Fig. 2. Its boundary is the bifurcation set. It will be locally seen a cusp.


Figure 2. Bifurcation set and the domain D1 for $S(x ; a, b)$.

The function $\mathrm{S}(\mathrm{x})$ has the two minimum points separated by a maximum with in D 1 , whereas outside it $\mathrm{S}(\mathrm{x})$ has a single minimum, which was given by Prof. Aoki using the concept of the cusp of Catastrophe theory with a potential $S(x)$. It is also seen that the two minimum points are put together and $S(x)$ has only one minimum point at the tip of the cusp (refer to information science research No. 12 [9], and also [4] and [8] for details).

In this paper, we shall extend the model to the autoregressive moving average $\operatorname{ARMA}(1,1)$ model and consider a problem similar to the misspecified MA(1) model fitting to AR(2) processes.

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## 2. Results on misspecified ARMA(1,1) model fitting

Let $\{Z(\mathrm{t})\}$ be a weakly stationary process with $E Z(t)=0$. $\{\mathrm{Z}(\mathrm{t})\}$ is said to satisfy a autoregressive moving average model of order p and $\mathrm{q}(\operatorname{ARMA}(\mathrm{p}, \mathrm{q})$ model $)$ if $\{\mathrm{Z}(\mathrm{t})\}$ is expressed as

$$
\begin{equation*}
\left(1-a_{1} B-\ldots-a_{p} B^{p}\right) \mathrm{Z}(\mathrm{t})=\left(1+b_{1} B+\ldots+b_{q} B^{q}\right) \mathrm{e}(\mathrm{t}), \tag{2.1}
\end{equation*}
$$

where $\{\mathrm{e}(\mathrm{t})\}$, t being an integer, consists of independently and identically distributed random variables with $E[e(t)]=0$, $E\left[e(t)^{2}\right]=\sigma^{2}$, the $a_{p}{ }^{\prime} \mathrm{s}$ and $b_{q}$ 's are constants which are independent of t , and B is the usual backshift operator such that $B[e(t)]=e(t-1)$ and $B^{k}[e(t)]=B\left[B^{k-1}[e(t)]\right]$ for $\mathrm{k}=1,2, .$. (see, for example, [2], [3]).
Let

$$
\begin{gather*}
\phi(B)=1-a_{1} B-\ldots-a_{p} B^{p}=\prod_{k=1}^{p}\left(1-\phi_{k} B\right),  \tag{2.2}\\
\theta(B)=1+b_{1} B+\ldots+b_{q} B^{q}=\prod_{k=1}^{q}\left(1-\theta_{k} B\right) . \tag{2.3}
\end{gather*}
$$

In our model fitting, it is assumed that $\left|\phi_{h}\right|<1,\left|\theta_{k}\right| \leq 1$ for all $\mathrm{h}=1,2, \cdots, \mathrm{p}$, and $\mathrm{k}=1,2, \cdots$, q . Let $\Theta=$ $\left(\phi_{1}, \ldots, \phi_{p}, \theta_{1}, . ., \theta \mathrm{q}\right)$ be a $(\mathrm{p}+\mathrm{q})$-dimensional unknown parameter, and let $\left\{F_{k}(\Theta)\right\}$ be a sequence of functions of $\Theta$, which are defined in the following way. For $\mathrm{t}>0$,

$$
\begin{equation*}
\mathrm{e}(\mathrm{t})=\left\{\prod_{k=1}^{p}\left(1-\phi_{k} B\right) \prod_{k=1}^{q}\left(1-\theta_{k} B\right)^{-1}\right\} \mathrm{Z}(\mathrm{t})=\left\{\sum_{k=1}^{\infty} F_{k}(\Theta) B^{k}\right\} Z(t) \tag{2.4}
\end{equation*}
$$

For evaluating the asymptotic properties of the conditional quasi-maximum likelihood estimators of $\Theta$ when the sample size tends to infinity, we should attend to a function

$$
\begin{align*}
& S_{p, q}(\Theta)=E\left[e(t)^{2}\right]  \tag{2.5}\\
& =\int_{-1 / 2}^{1 / 2} \frac{\left|\prod_{k=1}^{p}\left[1-\phi_{k} \exp (-2 \pi i \omega)\right]\right|^{2}}{\left|\prod_{j=1}^{q}\left[1-\theta_{j} \exp (-2 \pi i \omega)\right]\right|^{2}} f_{Z}(\omega) d \omega
\end{align*}
$$

The value $\hat{\Theta}$ which minimizes $S_{p, q}(\Theta)$ with respect to $\Theta$ should be obtained (see Tanaka and Huzii [10] and also Huzii [5]).
The spectrum of an $\operatorname{ARMA}(\mathrm{p}, \mathrm{q})$ process $f_{Z}(\omega)$ is given by

$$
\begin{equation*}
f_{Z}(\omega)=\frac{\sigma^{2}}{2 \pi} \frac{\left|\theta\left(e^{-i \omega}\right)\right|^{2}}{\left|\phi\left(e^{-i \omega}\right)\right|^{2}} . \tag{2.6}
\end{equation*}
$$

AR and MA spectra are special cases of this spectrum when $\theta(x)=1$ and $\phi(x)=1$, respectively.
Therefore if the process $\{\mathrm{Z}(\mathrm{t})\}$ is an $\operatorname{ARMA}(\mathrm{p}, \mathrm{q})$ process and is correctly fitted by the ARMA $(\mathrm{p}, \mathrm{q})$ model, then we have $S_{p, q}(\Theta)=\frac{\sigma^{2}}{2 \pi}$, which is a spectral density of a white noise process.
Let $\{\mathrm{X}(\mathrm{t})\}$ be a weakly stationary process with mean $E[X(t)]=0$ and spectral density $f_{X}(\omega)$. When we consider an $\operatorname{ARMA}(\mathrm{p}, \mathrm{q})$ model fitting to this process $\{\mathrm{X}(\mathrm{t})\}$, then $S_{p, q}(\Theta)$ is expressed as

$$
\begin{equation*}
S_{p, q}(\Theta)=\int_{-1 / 2}^{1 / 2} \frac{\left|\Pi_{k=1}^{p}\left[1-\phi_{k} \exp (-2 \pi \mathrm{i} \omega)\right]\right|^{2}}{\mid \prod_{j=1}^{q}\left[1-\left.\theta_{j} \exp (-2 \pi \mathrm{i} \omega)\right|^{2}\right.} f_{X}(\omega) d \omega . \tag{2.7}
\end{equation*}
$$

In this paper, consideration is given to the case when an $\operatorname{ARMA}(1,1)$ model is fitted incorrectly to an $\operatorname{AR}(2)$ process $\{\mathrm{X}(\mathrm{t})\} ;\left(1-a B-b B^{2}\right) \mathrm{X}(\mathrm{t})=\mathrm{e}(\mathrm{t})$. Here we set the $\operatorname{ARMA}(1,1)$ model parameters $(x, y)$ in stead of $(\phi, \theta)$. In this case, $S_{p, q}(\Theta)$ can be derived from (2.7), ignoring the constant term $\frac{\sigma^{2}}{2 \pi}$, as

$$
\begin{align*}
& S_{11}(x, y)=S_{1,1}(x, y ; a, b) \\
& \quad=\frac{1+b-2 a x+(1+b) x^{2}+\left(-a(1-b)+2\left(1-b^{2}\right) x-a(1-b) x^{2}\right) y-b\left(1+b-2 a x+(1+b) x^{2}\right) y^{2}}{(1-b)\left(1-a^{2}+2 b+b^{2}\right)\left(1-y^{2}\right)\left(1+a y+b y^{2}\right)} . \tag{2.8}
\end{align*}
$$

If we fit the $\operatorname{ARMA}(1,1)$ model to a special $\operatorname{AR}(2)$ process, the function $S_{11}(x, y)$ will have two minimal points. For a example, we have the following graph for an $\operatorname{AR}(2)$ process whose parameters are $a=0.4, b=0.9$.


Figure 3. Cross section of $S_{11}(x, y)$ with $a=0.4, b=0.9$.

In order to investigate the minimal point of the function $S_{11}(x, y)$, it is first necessary to consider its locally minimal points on the admissible parameter space $(\Omega)$ of $\operatorname{AR}(2)$ process with parameters a and b , where

$$
\Omega=\{(a, b) ; 0 \leq(b+a+1)(b-a+1),-2 \leq a \leq 2,-1 \leq b \leq 1\} .
$$

The locally minimal and maximal points satisfy the following equations,

$$
\begin{align*}
& \frac{\partial S_{11}(x, y)}{\partial_{x}}=0  \tag{2.9}\\
& \frac{\partial S_{11}(x, y)}{\partial_{y}}=0 \tag{2.10}
\end{align*}
$$

We shall solve the equations. The equation (2.9) is equivalent to

$$
\begin{equation*}
a-x-b x-y+b^{2} y+a x y-a b x y-a b y^{2}+b x y^{2}+b^{2} x y^{2}=0 \tag{2.11}
\end{equation*}
$$

Then we have

$$
\begin{equation*}
x=\frac{a+\left(-1+b^{2}\right) y-a b y^{2}}{1+b-a y+a b y-b y^{2}-b^{2} y^{2}} . \tag{2.12}
\end{equation*}
$$

Also the equation (2.10) is equivalent to the following equation,

```
a-x-\mp@subsup{a}{}{2}x+\mp@subsup{b}{}{2}x+a\mp@subsup{x}{}{2}-y+by+2\mp@subsup{b}{}{2}y+2axy-4abxy-\mp@subsup{x}{}{2}y+b\mp@subsup{x}{}{2}y+2\mp@subsup{b}{}{2}\mp@subsup{x}{}{2}y-a\mp@subsup{y}{}{2}-2ab\mp@subsup{y}{}{2}+a\mp@subsup{b}{}{2}\mp@subsup{y}{}{2}-
    x y 2}+3\mp@subsup{a}{}{2}x\mp@subsup{y}{}{2}+bx\mp@subsup{y}{}{2}-\mp@subsup{a}{}{2}bx\mp@subsup{y}{}{2}+\mp@subsup{b}{}{2}x\mp@subsup{y}{}{2}-\mp@subsup{b}{}{3}x\mp@subsup{y}{}{2}-a\mp@subsup{x}{}{2}\mp@subsup{y}{}{2}-2ab\mp@subsup{x}{}{2}\mp@subsup{y}{}{2}+a\mp@subsup{b}{}{2}\mp@subsup{x}{}{2}\mp@subsup{y}{}{2}+\mp@subsup{a}{}{2}\mp@subsup{y}{}{3}-2b\mp@subsup{y}{}{3}-\mp@subsup{a}{}{2}b\mp@subsup{y}{}{3}
    2b ' y 3}-2ax\mp@subsup{y}{}{3}+4abx\mp@subsup{y}{}{3}+2a\mp@subsup{b}{}{2}x\mp@subsup{y}{}{3}+\mp@subsup{a}{}{2}\mp@subsup{x}{}{2}\mp@subsup{y}{}{3}-2b\mp@subsup{x}{}{2}\mp@subsup{y}{}{3}-\mp@subsup{a}{}{2}b\mp@subsup{x}{}{2}\mp@subsup{y}{}{3}-2\mp@subsup{b}{}{2}\mp@subsup{x}{}{2}\mp@subsup{y}{}{3}+2ab\mp@subsup{y}{}{4}-a\mp@subsup{b}{}{2}\mp@subsup{y}{}{4}-3bx\mp@subsup{y}{}{4}
    a

From (2.12) and (2.13),
\[
\begin{equation*}
\frac{(1-a+b)(1+a+b)(a+b(1+b) y)\left(-1+y^{2}\right)^{2}\left(b-a y+a b y-2 b y^{2}+b^{3} y^{4}\right)}{\left(-1+a y+b^{2} y^{2}+b\left(-1-a y+y^{2}\right)\right)^{2}}=0 . \tag{2.14}
\end{equation*}
\]

Therefore in order to have a real solution ( \(\mathrm{x}, \mathrm{y}\) ) of the equations (2.9) and (2.10), it is necessary to have a real solution y of the equation (2.14) on the parameter space \(\Omega\). Then it is essentially equivalent to
\[
\begin{equation*}
\left(a+b y+b^{2} y\right)\left(b-a y+a b y-2 b y^{2}+b^{3} y^{4}\right)=0 . \tag{2.15}
\end{equation*}
\]

In general, it is very difficult to solve the equation, but to know the number of the real solutions it is sufficient to consider the resultant of the polynomial
\[
\begin{equation*}
f(y)=\left(a+b y+b^{2} y\right)\left(b-a y+a b y-2 b y^{2}+b^{3} y^{4}\right) . \tag{2.16}
\end{equation*}
\]

Since the derivative of \(f\) is given by
\[
\begin{equation*}
\frac{\partial}{\partial y} f(y)=-a^{2}+a^{2} b+b^{2}+b^{3}-6 a b y+2 a b^{3} y-6 b^{2} y^{2}-6 b^{3} y^{2}+4 a b^{3} y^{3}+5 b^{4} y^{4}+5 b^{5} y^{4} \tag{2.17}
\end{equation*}
\]
the resultant of the two polynomials (2.16) and (2.17) on \(y\) is give as
\[
\begin{align*}
& R(a, b)=(-1+a-b)^{2}(-1+b)^{2} b^{16}(1+b)(1+a+b)^{2}\left(a-b-b^{2}\right)^{2} \times  \tag{2.18}\\
& \quad\left(a+b+b^{2}\right)^{2}\left(32 a^{2}-27 a^{4}+54 a^{4} b+256 b^{2}-288 a^{2} b^{2}-27 a^{4} b^{2}+512 b^{3}+256 b^{4}\right)
\end{align*}
\]

From the Catastrophe theory, a number of locally minimum points of \(S_{11}(x, y)\) on \(\Omega\) for \(\operatorname{AR}(2)\) process with parameters \((a, b)\) is explained by considering a change for the sign of the resultant \(R(a, b)\). If the two polynomials (2.16) and (2.17) have common zeros, the resultant must be vanished. Hence we consider the conditions for \(R(a, b)=0\) on \(\Omega=\{(a, b) ; 0 \leq\) \((b+a+1)(b-a+1),-2 \leq a \leq 2,-1 \leq b \leq 1\}\).
Since the polynomial;
\[
\begin{equation*}
\left(32 a^{2}-27 a^{4}+54 a^{4} b+256 b^{2}-288 a^{2} b^{2}-27 a^{4} b^{2}+512 b^{3}+256 b^{4}\right) \tag{2.19}
\end{equation*}
\]
in (10) is always non-negative on \(\Omega\) (see Appendix), it is sufficient to consider the zeros of a polynomial
\[
\begin{equation*}
\operatorname{g} 1(a, b)=(-1+a-b)(-1+b) b(1+b)(1+a+b)\left(a-b-b^{2}\right)\left(a+b+b^{2}\right) . \tag{2.20}
\end{equation*}
\]

We have the following graph of a contour of \(\mathrm{g} 1(\mathrm{a}, \mathrm{b})=0\) on \(\Omega\).


Figure 4. A contour line of \(\mathrm{g} 1(\mathrm{a}, \mathrm{b})=0\) for \(\operatorname{AR}(2)\) parameters \((a, b)\)

It turns out that the function \(S_{11}(x, y)\) has the two minimum points in a domain (D2) of a portion with a deep color surrounded with the curve in Fig.5, where
\[
\begin{equation*}
\mathrm{D} 2=\left\{(a, b) \in \Omega ;\left(a-b-b^{2}\right)\left(a+b+b^{2}\right)<0\right\} . \tag{2.21}
\end{equation*}
\]

Also we define the (bifurcation) set
\[
\begin{equation*}
\mathrm{B} 2=\left\{(a, b) \in \Omega ;\left(a-b-b^{2}\right)\left(a+b+b^{2}\right)=0\right\} . \tag{2.22}
\end{equation*}
\]

When numerical integration is performed using Mathematica (Ver.9), it turns out that the area of this domain D2 will be 2.0 square, and the rate to the parameter space of a lower triangle will be \(50 \%\) exactly. It means that the domain D2 where \(S_{11}(x, y)\) has 2 minimum points becomes about 3 times larger than the area of the domain D1 shown in Fig.2, since its area is about \(0.70(17.6 \%)\).


Figure 5. The domain D 2 for \(\mathrm{AR}(2)\) parameters \((a, b)\).

We determine the form of \(S_{11}(x, y)\) at every point in D 2 , by considering only one point within each of the domain in the next section.

\section*{3. Illustrations and simulation}

\subsection*{3.1 Illustrations}

By varying the \(\mathrm{AR}(2)\) parameters, \(a\) and \(b\), continuously and staying inside of D 2 , for example, going from position P1 to P2 in Fig.6, the system remains in a stable equilibrium that is the function \(S_{11}(x, y)\) has two minima. However, if \(a\) and \(b\) are changed so that the bifurcation set B2 is transversed, something unusual happens. To see this, start in position P2 of Fig.6, where the system is in a stable equilibrium. Moving parallel to the \(a\)-axis toward position P3, when position P 3 is reached, the system becomes unstablethe and the function \(S_{11}(x, y)\) has only one minima. There the system is stable again and remains so while moving onward to position P 4 . In position P 5 inside of D 2 , it is also seen that the function \(S_{11}(x, y)\) has two minima.


Figure 6. Selected parameters ( \(a, b\) ) of positions P1- P5.
[1] position P1; \(a=0.0\) and \(b=0.5\). In this case, \(S_{11}(x, y)\) has two locally minimum points on the parameter space \(\Omega\) at \(\{\mathrm{x}=-0.5, \mathrm{y}=0.732051\}\) and \(\{\mathrm{x}=0.5, \mathrm{y}=-0.732051\}\), which is shown in Fig.3.1.
[2] position \(\mathrm{P} 2 ; a=0.5\) and \(b=0.5\). In this case, \(S_{11}(x, y)\) has two locally minimum points on the parameter space \(\Omega\) at \(\{\mathrm{x}=-0.0417278, \mathrm{y}=0.604608\}\) and \(\{\mathrm{x}=0.867418, \mathrm{y}=-0.897478\}\), which is shown in Fig.3.2.
[3] position \(\mathrm{P} 3 ; a=0.75\) and \(b=0.5\) (lies in B2). In this case, \(S_{11}(x, y)\) has only one locally minimum point on the parameter space \(\Omega\) at \(\{\mathrm{x}=0.208367, \mathrm{y}=0.551929\}\), which is shown in Fig.3.3.
[4] position \(\mathrm{P} 4 ; a=1.0\) and \(b=0.5\). In this case, \(S_{11}(x, y)\) has only one locally minimum point on the parameter space \(\Omega\) at \(\{\mathrm{x}=0.467188, \mathrm{y}=0.505418\}\), which is shown in Fig.3.4.
[5] position P5; \(a=0.0\) and \(b=-0.8\). In this case, \(S_{11}(x, y)\) has two locally minimum points on the parameter space \(\Omega\) at \(\{\mathrm{x}=0.866025, \mathrm{y}=-0.732051\}\) and \(\{\mathrm{x}=-0.866025, \mathrm{y}=0.732051\}\), which is shown in Fig.3.5.

The following figures give qualitative graphs of \(S_{11}(x, y)\) for the parameters \((a, b)\) of positions P1- P5, respectively.


Figure 3.1. \(S_{11}(x, y)\) with \(a=0.0\) and \(b=0.5\).


Figure 3.3. \(S_{11}(x, y)\) with \(a=0.75\) and \(b=0.5\).


Figure 3.2. \(S_{11}(x, y)\) with \(a=0.5\) and \(b=0.5\).


Figure 3.4. \(S_{11}(x, y)\) with \(a=1.0\) and \(b=0.5\).


Figure 3.5. \(S_{11}(x, y)\) with \(a=0.0\) and \(b=-0.8\).

\subsection*{3.2 Simulation}

We generate a time series of length \(n=250\) from the \(\operatorname{AR}(2)\) models which are discussed above [1], \(\ldots\), [5], where the noise is generated from the normal distribution with mean 0 and variance 1 . Then we fit an ARMA \((1,1)\) model to each of the time series using the conditional maximum likelihood method with initial values of parameters for the arguments ( \(\mathrm{x}, y\) ) of the model. The calculations below are supported by the computer software Mathematica (V.9.0) and an application software ([5]).
[1] Case when \(\operatorname{AR}(2)\) process with parameters \((a, b)=(0.0,0.5)\).


Here is a plot of the data.


Here is the plot of the sample correlation function.


Here is the plot of the sample spectrum.

When we estimate the AR model parameters using the conditional maximum likelihood method, it turns out that AR(2) has a lower AIC value ( -0.191707 ).
\(\left(\begin{array}{ccr}1 & \text { ARModel }[\{-0.0105462\}, 1.03342] & 0.04087351 \\ 2 & \text { ARModel }[\{-0.0133694,-0.46747\}, 0.812445] & -0.191707 \\ 3 & \text { ARModel }[\{-0.0113916,-0.467345,0.00443366\}, 0.815708] & -0.179699 \\ 4 \\ 4 & \text { ARModel }[\{-0.0114683,-0.496194,0.00494844,-0.0610469\}, 0.812564] & -0.175561\end{array}\right)\)

Next we estimate the ARMA(1,1) model parameters using the conditional maximum likelihood method with some different initial parameter values. The initial parameter values \((x=-0.5, y=0.5)\) are provided as the arguments of ARMA model \((1,1)\). Then we have ARMA model \([\{x=-0.553568\},\{y=0.788606\}, 0.956614]\) as the conditional maximum likelihood estimate of an \(\operatorname{ARMA}(1,1)\) model.
On the other hand, different initial values \((x=0.5, y=-0.5)\) lead to another model, ARMA model [ \(\{x=0.546659\},\{y\) \(=-0.776022\}, 0.963346]\).
Therefore we can have two conditional maximum likelihood estimates of an \(\operatorname{ARMA}(1,1)\) model when we fit the ARMA \((1,1)\) model to the \(\operatorname{AR}(2)\) process with the parameters \((0.0,0.5)\), which corresponds to the discussion [5] in 3.1 and also Figure 3.5.
[2] Case when \(\operatorname{AR}(2)\) process with parameters \((a, b)=(0.5,0.5)\).


Here is a plot of the data.


Here is the plot of the sample correlation function.


Here is the plot of the sample spectrum.

When we estimate the AR model parameters using the conditional maximum likelihood method, it turns out that AR(2) has a lower AIC value \((-0.0608918)\).
\[
\left(\begin{array}{lccc}
1 & \text { ARModel }[\{0.345558\}, 1.13956] & 0.138642 & 1 \\
2 & \text { ARModel }[\{0.497681,-0.436744\}, 0.92599] & -0.0608918 & 2 \\
3 & \text { ARModel }[\{0.478082,-0.413745,-0.0474331\}, 0.927595] & -0.0511598 & 3 \\
4 & \text { ARModel }[\{0.479572,-0.403076,-0.0605061,0.0297809\}, 0.930096] & -0.0404674 & 4
\end{array}\right)
\]

Next we estimate the ARMA \((1,1)\) model parameters using the conditional maximum likelihood method with some different initial parameter values.
The initial parameter values \((x=0.7, y=-0.8)\) are provided as the arguments of ARMA model \((1,1)\). Then we have ARMA model \([\{x=0.877052\},\{y=-0.908966\}, 1.29477]\) as the conditional maximum likelihood estimate of an ARMA( 1,1 ) model.
On the other hand, different initial values \((x=-0.7, y=0.8)\) lead to another model, ARMA model \([\{x=0.0119532\}\), \(\{y=0.501642\}, 1.02417]\).
Therefore we have two conditional maximum likelihood estimates of an \(\operatorname{ARMA}(1,1)\) model when we fit the \(\operatorname{ARMA}(1,1)\) model to the \(\operatorname{AR}(2)\) process with the parameters \((0.5,0.5)\), which corresponds to the discussion [2] in 3.1 and also Figure 3.2.
[3] Case when \(\operatorname{AR}(2)\) process with parameters \((a, b)=(0.75,0.5)\).


Here is a plot of the data.


Here is the plot of the sample correlation function.


Here is the plot of the sample spectrum.

When we estimate the AR model parameters using the conditional maximum likelihood method, it turns out that AR(2) has a lower AIC value ( -0.191475 ).
\[
\left(\begin{array}{cccc}
1 & \text { ARModel }[\{0.508648\}, 1.04106] & 0.0482427 & 1 \\
2 & \text { ARModel }[\{0.74941,-0.471886\}, 0.812634] & -0.191475 & 2 \\
3 & \text { ARModel }[\{0.738451,-0.45428,-0.0234112\}, 0.815471] & -0.17999 & 3 \\
4 & \text { ARModel }[\{0.7365,-0.486534,0.0305719,-0.0714131\}, 0.811182] & -0.177263 & 4
\end{array}\right)
\]

Next we estimate the ARMA(1,1) model parameters using the conditional maximum likelihood method with some different initial parameter values.
The initial parameter values \((x=0.7, y=-0.8)\) are provided as the arguments of ARMA model \((1,1)\). Then we have ARMA model \([\{x=0.187419\},\{y=0.583655\}, 0.86927]\) as the conditional maximum likelihood estimate of an ARMA( 1,1 ) model.
Different initial values \((x=-0.7, y=0.8)\) lead to the same model.
Therefore we have only one conditional maximum likelihood estimate of an \(\operatorname{ARMA}(1,1)\) model when we fit the ARMA(1,1) model to the AR(2) process with the parameters ( \(0.75,0.5\) ), which corresponds to the discussion [3] in 3.1
and also Figure 3.3.
[4] Case when \(\mathrm{AR}(2)\) process with parameters \((a, b)=(1.0,0.5)\).


Here is a plot of the data.


Here is the plot of the sample correlation function.


Here is the plot of the sample spectrum.

When we estimate the AR model parameters from the data using the conditional maximum likelihood method, it turns out that AR(2) has a lower AIC value ( -0.190295 ).
\(\left(\begin{array}{cccc}1 & \text { ARModel }[\{0.671852\}, 1.07934] & 0.0843472 & 1 \\ 2 & \text { ARModel }[\{1.00781,-0.499501\}, 0.813593] & -0.190295 & 2 \\ 3 & \text { ARModel }[\{0.988389,-0.46024,-0.0390077\}, 0.815645] & -0.179776 & 3 \\ 4 & \text { ARModel }[\{0.986122,-0.485076,0.0157204,-0.053866\}, 0.813146] & -0.174845 & 4\end{array}\right)\)

Next we estimate the ARMA(1,1) model parameters using the conditional maximum likelihood method with some different initial parameter values.
The initial parameter values \((x=0.7, y=-0.8)\) are provided as the arguments of ARMA model \((1,1)\). Then we have ARMA model \([\{x=0.458668\},\{y=0.535122\}, 0.874477]\) as the conditional maximum likelihood estimate of an ARMA( 1,1 ) model.
On the other hand, different initial values \((x=0.5, y=-0.5)\) lead to another model, ARMA model \([\{x=0.458677\},\{y\)
\(=0.535107\}, 0.874477]\).
Therefore we have two conditional maximum likelihood estimates of an \(\operatorname{ARMA}(1,1)\) model when we fit the ARMA \((1,1)\) model to the \(\operatorname{AR}(2)\) process with the parameters (1.0, 0.5), which corresponds to the discussion [4] in 3.1 and also Figure 3.4.
[5] Case when \(\operatorname{AR}(2)\) process with the parameters \((a, b)=(0.0,-0.8)\).


Here is a plot of the data.


Here is the plot of the sample correlation function.


Here is the plot of the sample spectrum.

When we estimate the AR model parameters from the data using the conditional maximum likelihood method, it turns out that \(\operatorname{AR}(2)\) has a lower AIC value. If we fit an \(\operatorname{AR}(2)\) model to the data, the conditional maximum likelihood estimates are given as AR model [ \(\{-0.0309124,0.778491\}, 0.907196]\), which means that \(a=-0.0309124, b=0.77849\) and \(\sigma^{2}=0.907196\).
\[
\left(\begin{array}{lccc}
1 & \text { ARModel }[\{-0.13487\}, 2.26939] & 0.82751 & 1 \\
2 & \text { ARModel }[\{-0.0309124,0.778491\}, 0.907196] & -0.0813971 & 2 \\
3 & \text { ARModel }[\{0.0045962,0.7732,-0.0419463\}, 0.897542] & -0.0840948 & 3 \\
4 & \text { ARModel }[\{0.0137434,0.791136,-0.0465155,-0.0261294\}, 0.893215] & -0.0809279 & 4
\end{array}\right)
\]

Next we estimate the ARMA(1,1) model parameters using the conditional maximum likelihood method with some different initial parameter values.

The initial parameter values \((x=-0.5, y=0.5)\) are provided as the arguments of ARMA model \((1,1)\). Then we have ARMA model \([\{x=-0.966694\},\{y=0.820735\}, 1.66297]\) as the conditional maximum likelihood estimate of an ARMA \((1,1)\) model.
On the other hand, different initial values \((x=0.5, y=-0.5)\) lead to another model, ARMA model \([\{x=0.958326\}\), \(\{y\) \(=-0.845974\}, 2.02728]\).
Therefore, depending on the initial parameter values, we have two conditional maximum likelihood estimates of an \(\operatorname{ARMA}(1,1)\) model when we fit the \(\operatorname{ARMA}(1,1)\) model to the \(\operatorname{AR}(2)\) process with the parameters \((0.0,-0.8)\), which corresponds to the case [5] in 3.1 and also Figure 3.5.

\section*{4. Conclusion}

In this paper, we have considered the misspecified \(\operatorname{ARMA}(1,1)\) model fitting to \(\operatorname{AR}(2)\) processes. The conditions for \(\operatorname{AR}(2)\) parameters on which \(\operatorname{ARMA}(1,1)\) quasi-likelihood function has more than one local maximum points in the stationary and invertible parameter space were given as the domain D 2 for \(\mathrm{AR}(2)\) parameters \((a, b)\), and it was shown in Fig.5. It related to critical point theory and the behaviour of degenerate critical points of the function of two variables in Catastrophe theory, considering the ARMA(1,1) quasi-likelihood function as a potential function with two external parameters \(a\) and \(b\). On the misspecified MA(1) model fitting to \(\operatorname{AR}(2)\) processes, it is already seen that the domain for \(\operatorname{AR}(2)\) parameters on which the \(\mathrm{MA}(1)\) quasi-likelihood function has more than one local maximum points is related to a cusp catastrophe. Our result presented in this paper will be also explained completely by using Catastrophe Theory.

Applying a stationary ARMA model to time series data in actual data analysis, there is a possibility that two or more candidates for the model parameters exist, and then we cannot estimate the parameters of the model well. We also know that the ARMA \((1,1)\) model seems to be more sensitive than MA (1) model about incorrect discernment. Therefore, if such a phenomenon appears in the parameter estimation for an ARMA model fitting, the applied model must be different from a true (or proper) model, and then we should change the model immediately.

\section*{Appendix}

We should check the local maximal or minimal values of
\[
\begin{equation*}
\operatorname{g} 2(a, b)=\left(32 a^{2}-27 a^{4}+54 a^{4} b+256 b^{2}-288 a^{2} b^{2}-27 a^{4} b^{2}+512 b^{3}+256 b^{4}\right), \text { say. } \tag{A1}
\end{equation*}
\]

Then we have
\[
\begin{align*}
& \frac{\partial \mathrm{g} 2(a, b)}{\partial_{a}}=64 a-108 a^{3}+216 a^{3} b-576 a b^{2}-108 a^{3} b^{2}=0,  \tag{A2}\\
& \frac{\partial \mathrm{~g} 2(a, b)}{\partial_{b}}=54 a^{4}+512 b-576 a^{2} b-54 a^{4} b+1536 b^{2}+1024 b^{3}=0 \tag{A3}
\end{align*}
\]

The solutions of real number for the equations (10) and (11) in \(\Omega=\{(a, b) ; 0 \leq(b+a+1)(b-a+1),-2 \leq a \leq 2,-1 \leq b \leq 1\}\) are
\[
\{a=0, b=-1\},\left\{a=0, b=-\frac{1}{2}\right\},\{a=0, b=0\}
\]
\[
\left\{a=-\frac{4}{3} \sqrt{-10+\sqrt{105}}, b=\frac{1}{12}(9-\sqrt{105})\right\} \text { and }\left\{a=\frac{4}{3} \sqrt{-10+\sqrt{105}}, b=\frac{1}{12}(9-\sqrt{105})\right\} .
\]

The local maximal or minimal values of \(\mathrm{g} 2(\mathrm{a}, \mathrm{b})\) at those points are \(\{0,16,0,8.561,8.561\}\), respectively. Also \(g 2(a, b) \geq\) 0 on the boundary of \(\Omega\). Thus the minimum of the function \(g 2(a, b)\) is 0 at \((a, b)=(0,-1)\) and \((0,0)\).

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